



## **Fixed Point Theorems for Presic Type Mappings in $G_p$ -Metric Spaces**

**Cafer Aydin<sup>1\*</sup> and Seher Sultan Sepet<sup>1</sup>**

<sup>1</sup>*Department of Mathematics, Kahramanmaraş Sütçü İmam University, Kahramanmaraş, 46100, Turkey.*

### **Authors' contributions**

*This work was carried out in collaboration between both authors. Both authors read and approved the final manuscript.*

### **Article Information**

DOI: 10.9734/JAMCS/2017/35967

*Editor(s):*

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Complete Peer review History: <http://www.sciedomain.org/review-history/21060>

*Received: 5<sup>th</sup> August 2017*

*Accepted: 15<sup>th</sup> September 2017*

*Published: 20<sup>th</sup> September 2017*

### **Original Research Article**

## **Abstract**

In this paper, we introduce some fixed point theorems in Presic type mappings on  $G_p$ -metric spaces. The present results generalizes various known results in the related literature.

**Keywords:** Fixed point,  $G_p$ -metric space, Contractive mapping

**2010 Mathematics Subject Classification:** 47H10, 54H25.

## **1 Introduction and Preliminaries**

In 1922, Banach [1] established famous fundamental fixed point theorem, also known as Banach contraction principle. The Banach contraction principle is the simplest and one of the most versatile

\*Corresponding author: E-mail: caydin61@gmail.com;

elementary results in fixed point theory. Over the years, various extensions and generalizations of this principle have appeared in the literature. Matthews [2], introduced the partial metric spaces and proved a fixed point theorem on this space. After that several fixed point results have been proved in this space, for more details see [3] [4] [5] [6] [7]. In 2006, Mustafa and Sims [8] introduced a new structure called G-metric space as a generalization of the usual metric spaces. Afterwards based on the notion of a G-metric space, many fixed point results for different contractive conditions have been presented, for more details see [9] [10] [11] [12] [13]. Recently, based on the two above metric spaces, Zand and Nezhad [14] introduced a new generalized metric spaces  $G_p$  as a both generalization of the partial metric space and G-metric spaces. Some of these works may be noted in [15] [16] [17].

Now, we mention briefly some fundamental definitions.

**Definition 1.1.** [14] Let  $X$  be a nonempty set and let  $G_p : X \times X \times X \rightarrow \mathbb{R}^+$  be a function satisfying the following properties:

- (GP1)  $0 \leq G_p(x, x, x) \leq G_p(x, x, y) \leq G_p(x, y, z)$ , all  $x, y, z \in X$ ;
- (GP2)  $G_p(x, y, z) = G_p(x, z, y) = G_p(y, z, x) \dots$ , (symmetry in all three variables);
- (GP3)  $G_p(x, y, z) \leq G(x, a, a) + G_p(a, y, z) - G_p(a, a, a)$ , for any  $a, x, y, z \in X$ , (rectangle inequality);
- (GP4)  $x = y = z$  if  $G_p(x, y, z) = G_p(x, x, x) = G_p(y, y, y) = G_p(z, z, z)$ ;

Then the pair  $(X, G_p)$  is called a  $G_p$ -metric space.

**Proposition 1.1.** [14] Let  $(X, G_p)$  be a  $G_p$ -metric space. Then for any  $x, y, z$  and  $a \in X$  the following relations are true.

- (i)  $G_p(x, y, z) \leq G_p(x, x, y) + G_p(x, x, z) - G_p(x, x, x)$ ;
- (ii)  $G_p(x, y, y) \leq 2G_p(x, x, y) - G_p(x, x, x)$ ;
- (iii)  $G_p(x, y, z) \leq G_p(x, a, a) + G_p(y, a, a) + G_p(z, a, a) - 2G_p(a, a, a)$ ;
- (iv)  $G_p(x, y, z) \leq G_p(x, a, z) + G_p(a, y, z) - G_p(a, a, a)$ .

**Definition 1.2.** [14] Let  $(X, G_p)$  be a  $G_p$ -metric space and a sequence  $\{x_n\}$  is called a  $G_p$  convergent to  $x \in X$  if

$$\lim_{n,m \rightarrow \infty} G_p(x, x_n, x_m) = G_p(x, x, x).$$

A point  $x \in X$  is said to be limit point of the sequence  $\{x_n\}$  and written  $x_n \rightarrow x$ .

Thus if  $x_n \rightarrow x$  in a  $G_p$  metric space  $(X, G_p)$ , then for any  $\epsilon > 0$ , there exists  $\ell \in \mathbb{N}$  such that  $|G_p(x, x_n, x_m) - G_p(x, x, x)| < \epsilon$ , for all  $n, m > \ell$ .

**Proposition 1.2.** [14] Let  $(X, G_p)$  be a  $G_p$ -metric space, then for any sequence  $\{x_n\}$  in  $X$ , the following are equivalent that

- (i)  $\{x_n\}$  is  $G_p$  convergent to  $x$ ;
- (ii)  $G_p(x_n, x_n, x) \rightarrow G_p(x, x, x)$  as  $n \rightarrow \infty$ ;
- (iii)  $G_p(x_n, x, x) \rightarrow G_p(x, x, x)$  as  $n \rightarrow \infty$ .

**Definition 1.3.** [18]

- (1) The sequence  $\{x_n\}_{n \in \mathbb{N}}$  in a  $G_p$ -metric space  $(X, G_p)$  is said to be a  $G_p$  Cauchy sequence if there exists  $r \in \mathbb{R}$  such that  $\lim_{n,m \rightarrow \infty} G_p(x_n, x_m, x_m) = r$ .

(2)  $(X, G_p)$  is said to be  $G_p$ -complete if for every  $G_p$  Cauchy sequence  $\{x_n\}_{n \in \mathbb{N}}$  there exists  $x \in X$  such that

$$\lim_{n,m \rightarrow \infty} G_p(x_n, x_m, x_m) = \lim_{n,m \rightarrow \infty} G_p(x_n, x_m, x) = G_p(x, x, x).$$

**Lemma 1.1.** [15] Let  $(X, G_p)$  be a  $G_p$ -metric space. Then

- (i) If  $G_p(x, y, z) = 0$  then  $x = y = z$ ,
- (ii) If  $x \neq y$  then  $G_p(x, y, y) > 0$ .

**Proposition 1.3.** [14] Every  $G_p$ -metric space  $(X, G_p)$  defines a metric space  $(X, d_{G_p})$  as follows:

$$d_{G_p}(x, y) = G_p(x, y, y) + G_p(y, x, x) - G_p(x, x, x) - G_p(y, y, y), \text{ for all } x, y \in X.$$

## 2 Main Results

Considering the convergence of certain sequences S. B. Presic [19] generalized Banach contraction principle as follows:

**Theorem 2.1.** [19] Let  $(X, d)$  be a complete metric space,  $k$  a positive integer and  $T : X^k \rightarrow X$  a mapping satisfying the following contractive type condition

$$d(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1})) \leq q_1 d(x_1, x_2) + q_2 d(x_2, x_3) + \dots + q_k d(x_k, x_{k+1}) \quad (2.1)$$

for every  $x_1, x_2, \dots, x_{k+1}$  in  $X$  where  $q_1, q_2, \dots, q_k$  are non negative constants such that  $q_1 + q_2 + \dots + q_k < 1$ . Then there exist a point  $x$  in  $X$  such that  $T(x, x, \dots, x) = x$ . Moreover, if  $x_1, x_2, \dots, x_k$ , are arbitrary points in  $X$  and for  $n \in N$ ,

$$x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1}) \quad (n = 1, 2, \dots)$$

then the sequence  $\{x_n\}_{n=1}^{\infty}$  is convergent and

$$\lim x_n = T(\lim x_n, \lim x_n, \dots, \lim x_n).$$

Remark that condition (2.1) in the case  $k = 1$  reduces to the well-known Banach contraction mapping principle. So, Theorem 2.1 is a generalization of the Banach fixed point theorem.

Ćirić and Presic [20], generalized Theorem 2.1 as follows:

**Theorem 2.2.** [20] Let  $(X, d)$  be a complete metric space,  $k$  a positive integer and  $T : X^k \rightarrow X$  a mapping satisfying the following contractive type condition

$$d(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1})) \leq \lambda \max_{1 \leq i \leq k} \{d(x_i, x_{i+1})\} \quad (2.2)$$

where  $\lambda \in (0, 1)$  is constant and  $x_1, x_2, \dots, x_{k+1}$  in  $X$ . Then there exist a point  $x$  in  $X$  such that  $T(x, x, \dots, x) = x$ . Moreover, if  $x_1, x_2, \dots, x_k$ , are arbitrary points in  $X$  and for  $n \in N$ ,

$$x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1}) \quad (n = 1, 2, \dots)$$

then the sequence  $\{x_n\}_{n=1}^{\infty}$  is convergent and

$$\lim x_n = T(\lim x_n, \lim x_n, \dots, \lim x_n).$$

If in addition we suppose that on a diagonal  $\Delta \subset X^k$

$$d(T(u, u, \dots, u), T(v, v, \dots, v)) < d(u, v) \quad (2.3)$$

holds for all  $u, v \in X$ , with  $u \neq v$ , then  $x$  is the unique point in  $X$  with  $T(x, x, \dots, x) = x$ .

Nazir and Abbas [21], proved common fixed point theorems of Presic type in partial metric space. Also, Dhasmana [22] showed a unique common fixed point theorem is obtained in settings of  $G$ -metric spaces by using the concept of Presic fixed point theorem. Further, Gairola and Dhasmana [23] proved common fixed point theorems of Presic type in  $G$ -metric space which extends the result of Ćirić-Presic [20], Dhasmana [22] and George-Khan [24].

We will carry this idea to  $G_p$ -metric spaces, which is a generalization of partial metric spaces.

**Theorem 2.3.** *Let  $(X, G_p)$  be complete  $G_p$ -metric spaces,  $k$  a positive integer and  $T : X^k \rightarrow X$  a mapping satisfying the following contractive type condition*

$$G_p(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1}), T(x_3, x_4, \dots, x_{k+2})) \leq \lambda \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\} \quad (2.4)$$

where  $\lambda \in (0, 1)$  is constant and  $x_1, x_2, \dots, x_k$ , are arbitrary elements in  $X$ . Then there exists a point  $x$  in  $X$  such that  $T(x, x, \dots, x) = x$ . Moreover, if  $x_1, x_2, \dots, x_{k+2}$  are arbitrary points in  $X$  and  $n \in N$ ,

$$x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1}) \quad (n = 1, 2, \dots) \quad (2.5)$$

then the sequence  $\{x_n\}_{n=1}^{\infty}$  is convergent and

$$\lim_{n \rightarrow \infty} x_n = T(\lim x_n, \lim x_n, \dots, \lim x_n).$$

If in addition we suppose that

$$G_p(T(u, u, \dots, u), T(v, v, \dots, v), T(w, w, \dots, w)) < G_p(u, v, w) \quad (2.6)$$

holds for all  $u, v, w \in X$ , with  $u \neq v \neq w$ , then  $x$  is the unique point in  $X$  with  $T(x, x, \dots, x) = x$ .

*Proof.*  $x_1, x_2, \dots, x_k$ , be  $k$  arbitrary in  $X$ . Using these points define a sequence  $(x_n)$  as follows:

$$x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1}), \quad (n = 1, 2, \dots).$$

For simplicity set  $\gamma_n = G_p(x_n, x_{n+1}, x_{n+2})$ . We shall prove by induction that for each  $n \in N$ ;

$$\gamma_n \leq M\theta^n \quad (2.7)$$

where  $\theta = \lambda^{\frac{1}{k}}$  and  $M = \max\{\frac{\gamma_1}{\theta}, \frac{\gamma_2}{\theta^2}, \dots, \frac{\gamma_k}{\theta^k}\}$ . According to the definition of  $M$  we can writing for  $n = 1, 2, \dots, k$

$$\gamma_n \leq M\theta^n, \quad \gamma_{n+1} \leq M\theta^{n+1}, \dots, \gamma_{n+k-1} \leq M\theta^{n+k-1}.$$

Then we have:

$$\begin{aligned} \gamma_{n+k} &= G_p(x_{n+k}, x_{n+k+1}, x_{n+k+2}) \\ &= G_p(T(x_n, x_{n+1}, \dots, x_{n+k-1}), T(x_{n+1}, x_{n+2}, \dots, x_{n+k}), T(x_{n+2}, x_{n+3}, \dots, x_{n+k+1})). \end{aligned}$$

By (2.4)

$$\begin{aligned} \gamma_{n+k} &= G_p(T(x_n, x_{n+1}, \dots, x_{n+k-1}), T(x_{n+1}, x_{n+2}, \dots, x_{n+k}), T(x_{n+2}, x_{n+3}, \dots, x_{n+k+1})) \\ &\leq \lambda \max\{\gamma_n, \gamma_{n+1}, \gamma_{n+2}, \dots, \gamma_{n+k-1}\} \\ &\leq \lambda \max\{M\theta^n, M\theta^{n+1}, \dots, M\theta^{n+k-1}\} \end{aligned}$$

as  $\theta = \lambda^{\frac{1}{k}}$

$$\begin{aligned} \gamma_{n+k} &\leq \lambda M\theta^n \quad (\text{as } 0 < \theta < 1) \\ &= M\theta^{n+k} \end{aligned}$$

and the inductive proof of (2.7) is complete. Next using (2.7) for any  $n, m \in \mathbb{N}$  we have the following argument:

$$\begin{aligned}
G_p(x_n, x_m, x_m) &\leq G_p(x_n, x_{n+1}, x_{n+1}) + G_p(x_{n+1}, x_{n+2}, x_{n+2}) + \dots \\
&\quad + G_p(x_{m-1}, x_m, x_m) - \{G_p(x_{n+1}, x_{n+1}, x_{n+1}) + G_p(x_{n+2}, x_{n+2}, x_{n+2}) + \\
&\quad \dots + G_p(x_{m-1}, x_{m-1}, x_{m-1})\} \\
&\leq G_p(x_n, x_{n+1}, x_{n+2}) + G_p(x_{n+1}, x_{n+2}, x_{n+3}) + \dots + G_p(x_{m-2}, x_{m-1}, x_m) \\
&= \gamma_n + \gamma_{n+1} + \dots + \gamma_{m-2} \\
&\leq M\theta^n + M\theta^{n+1} + \dots + M\theta^{m-2} \\
&\leq \frac{M\theta^n}{1-\theta}
\end{aligned}$$

by which we conclude that  $(x_n)$  is a  $G_p$  Cauchy sequence. Since  $(X, G_p)$  is complete  $G_p$ -metric space, there exists  $x \in X$  such that  $\{x_n\}$  sequence converges  $x \in X$ . So,

$$\lim_{n,m \rightarrow \infty} G_p(x_n, x_m, x_m) = \lim_{n,m \rightarrow \infty} G_p(x_n, x_m, x) = G_p(x, x, x) = 0.$$

Then for any integer  $n$  we have

$$\begin{aligned}
G_p(x_{n+k}, x_{n+k}, T(x, x, \dots, x)) &= G_p(T(x, x, \dots, x), T(x_n, x_{n+1}, \dots, x_{n+k-1}, T(x_n, x_{n+1}, \dots, x_{n+k-1}))) \\
&\leq G_p(T(x, x, \dots, x), T(x, \dots, x, x_n), T(x, \dots, x, x_n)) + \\
&\quad G_p(T(x, \dots, x, x_n), T(x, \dots, x, x_n, x_{n+1}), T(x, \dots, x, x_n, x_{n+1})) + \\
&\quad G_p(T(x, \dots, x, x_n, x_{n+1}), T(x, \dots, x, x_n, x_{n+1}, x_{n+2}), T(x, \dots, x, x_n, x_{n+1}, x_{n+2})) \\
&\quad + \dots + G_p(T(x, x_n, \dots, x_{n+k-2}), T(x_n, x_{n+1}, \dots, x_{n+k-1}), T(x_n, x_{n+1}, \dots, x_{n+k-1})) \\
&\quad - \{G_p(T(x, \dots, x, x_n), T(x, \dots, x, x_n), T(x, \dots, x, x_n)) + \\
&\quad G_p(T(x, \dots, x, x_n, x_{n+1}), T(x, \dots, x, x_n, x_{n+1}), T(x, \dots, x, x_n, x_{n+1})) + \\
&\quad \dots + G_p(T(x, x_n, \dots, x_{n+k-2}), T(x_n, x_{n+1}, \dots, x_{n+k-2}), T(x_n, x_{n+1}, \dots, x_{n+k-2}))\} \\
&\leq G_p(T(x, x, \dots, x), T(x, \dots, x, x_n), T(x, \dots, x, x_n)) + \\
&\quad G_p(T(x, \dots, x, x_n), T(x, \dots, x, x_n, x_{n+1}), T(x, \dots, x, x_n, x_{n+1})) + \\
&\quad G_p(T(x, \dots, x, x_n, x_{n+1}), T(x, \dots, x, x_n, x_{n+1}, x_{n+2}), T(x, \dots, x, x_n, x_{n+1}, x_{n+2})) \\
&\quad + \dots + G_p(T(x, x_n, \dots, x_{n+k-2}), T(x_n, x_{n+1}, \dots, x_{n+k-1}), T(x_n, x_{n+1}, \dots, x_{n+k-1})) \\
&\leq \lambda \max\{G_p(x, x, x), G_p(x, x_n, x_n)\} + \lambda \max\{G_p(x, x, x), G_p(x, x_n, x_n), G_p(x_n, x_{n+1}, x_{n+1})\} + \\
&\quad \dots + \lambda \max\{G_p(x, x, x), G_p(x, x_n, x_n), G_p(x_n, x_{n+1}, x_{n+1}), \dots, G_p(x_{n+k-2}, x_{n+k-1}, x_{n+k-1})\}.
\end{aligned}$$

Taking the limit when  $n$  tends to infinity we obtain

$$G_p(x, x, T(x, x, \dots, x)) \leq \lambda G_p(x, x, x)$$

that is,

$$G_p(x, x, T(x, x, \dots, x)) \leq 0$$

which implies

$$T(x, x, \dots, x) = x.$$

Thus we proved that;

$$\lim x_n = T(\lim x_n, \lim x_n, \dots, \lim x_n).$$

Now suppose that (2.6) holds. To prove the uniqueness of the fixed point, let us assume that for some  $y, z \in X$ ,  $x \neq y \neq z$  we have

$$T(y, y, \dots, y) = y, \quad T(z, z, \dots, z) = z$$

Then by (2.6),

$$G_p(x, y, z) = G_p(T(x, x, \dots, x), T(y, y, \dots, y), T(z, z, \dots, z)) < G_p(x, y, z), \quad (2.8)$$

which is a contraction. So,  $x$  is the unique point in  $X$  such that  $T(x, x, \dots, x) = x$ .  $\square$

**Example 2.4.** Let  $X = [0, 2]$  and  $G_p : X \times X \times X \rightarrow \mathbb{R}^+$  defined by

$$G_p(x, y, z) = \begin{cases} |x - y| + |y - z| + |x - z|, & \text{if } x, y, z \in [0, 1] \\ \max\{x, y, z\}, & \text{otherwise} \end{cases}$$

$(X, G_p)$  is a complete  $G_p$  metric space. Let  $k \in \mathbb{Z}^+$  and  $T : X^k \rightarrow X$  be the mapping defined by

$$T(x_1, x_2, \dots, x_k) = \begin{cases} \frac{x_1 + x_k}{4k}, & \text{if } x_1, x_2, \dots, x_k \in [0, 1] \\ 0, & \text{otherwise} \end{cases}$$

Now  $x_1, x_2, \dots, x_k, x_{k+1}, x_{k+2} \in [0, 1]$  and  $\lambda = \frac{1}{2}$ . Thus, we obtain

$$\begin{aligned} & G_p(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1}), T(x_3, x_4, \dots, x_{k+2})) \\ &= \left| \frac{x_1 + x_k}{4k} - \frac{x_2 + x_{k+1}}{4k} \right| + \left| \frac{x_2 + x_{k+1}}{4k} - \frac{x_3 + x_{k+2}}{4k} \right| + \left| \frac{x_3 + x_{k+2}}{4k} - \frac{x_1 + x_k}{4k} \right| \\ &\leq \frac{1}{4k} [|x_1 - x_2| + |x_2 - x_3| + |x_1 - x_3| + |x_k - x_{k+1}| + |x_{k+1} - x_{k+2}| + |x_k - x_{k+2}|] \\ &= \frac{1}{4k} |G_p(x_1, x_2, x_3) + G_p(x_k, x_{k+1}, x_{k+2})| \\ &\leq \frac{1}{2k} \max\{G_p(x_1, x_2, x_3), G_p(x_k, x_{k+1}, x_{k+2})\} \\ &\leq \frac{1}{2k} \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\} \\ &\leq \frac{1}{2} \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\} \\ &= \lambda \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\}. \end{aligned}$$

If  $x_1, x_2, \dots, x_k \in [0, 1]$  and  $x_{k+1}, x_{k+2} \in [1, 2]$  then

$$\begin{aligned} G_p(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1}), T(x_3, x_4, \dots, x_{k+2}))) &= \frac{x_1 + x_k}{4k} \\ &\leq \frac{1}{2k} x_k \\ &\leq \frac{1}{2} \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\} \\ &= \lambda \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\}. \end{aligned}$$

If  $x_1, x_2, \dots, x_k, x_{k+1} \in [0, 1]$  and  $x_{k+2} \in [1, 2]$  then

$$\begin{aligned} G_p(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1}), T(x_3, x_4, \dots, x_{k+2}))) &= \left| \frac{x_1 + x_k}{4k} - \frac{x_2 + x_{k+1}}{4k} \right| \\ &\leq \frac{1}{2k} \max\{x_k, x_{k+1}\} \\ &\leq \frac{1}{2} \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\} \\ &= \lambda \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\}. \end{aligned}$$

Similarly, if  $x_1, x_2, \dots, x_k, x_{k+2} \in [0, 1)$  and  $x_{k+1} \in [1, 2]$  then

$$\begin{aligned} G_p(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1}), T(x_3, x_4, \dots, x_{k+2}))) &= \left| \frac{x_1 + x_k}{4k} - \frac{x_3 + x_{k+2}}{4k} \right| \\ &\leq \frac{1}{2k} \max\{x_k, x_{k+2}\} \\ &\leq \frac{1}{2} \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\} \\ &= \lambda \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\}. \end{aligned}$$

When some  $x_j \in [1, 2]$  and  $x_1, x_2, \dots, x_{j-1}, x_{j+1}, \dots, x_k, x_{k+1}, x_{k+2} \in [0, 1)$  or  $x_1, x_2, \dots, x_k, x_{k+1}, x_{k+2} \in [1, 2]$  then we obtain

$$\begin{aligned} G_p(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1}), T(x_3, x_4, \dots, x_{k+2}))) &= 0 \\ &\leq \lambda \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\}. \end{aligned}$$

Thus  $T$  satisfies (2.4) with  $\lambda = \frac{1}{2}$  and we have  $T(x, x, \dots, x) = x$ . Moreover for all  $x, y, z \in X$  with  $x \neq y \neq z$

$$G_p(T(x, x, \dots, x), T(y, y, \dots, y), T(z, z, \dots, z)) < G_p(x, y, z).$$

Thus all required hypotheses of Theorem (2.3) are satisfied. Furthermore, for any arbitrary points  $x_1, x_2, \dots, x_k \in X$ , the sequence  $(x_n)$  defined by (2.5) converges to  $x = 0$ , the unique fixed point of  $T$ .

**Corollary 2.5.** Let  $(X, G_p)$  be complete  $G_p$ -metric spaces,  $k \in \mathbb{Z}^+$  and  $T : X^k \rightarrow X$  a mapping satisfying the following contractive type condition

$$G_p(T(x_1, x_2, \dots, x_k), T(x_2, x_3, \dots, x_{k+1}), T(x_3, x_4, \dots, x_{k+2}))) \leq \sum_{i=1}^k \lambda_i G_p(x_i, x_{i+1}, x_{i+2}) \quad (2.9)$$

where  $\lambda_1, \lambda_2, \dots, \lambda_k$  are non-negative constants,  $\sum_{i=1}^k \lambda_i \in (0, 1)$  and  $x_1, x_2, \dots, x_k$ , are arbitrary elements in  $X$ . Then there exists a point  $x$  in  $X$  such that  $T(x, x, \dots, x) = x$ . Moreover, if  $x_1, x_2, \dots, x_{k+2}$  are arbitrary points in  $X$  and  $n \in N$ ,

$$x_{n+k} = T(x_n, x_{n+1}, \dots, x_{n+k-1}) \quad (n = 1, 2, \dots) \quad (2.10)$$

then the sequence  $\{x_n\}_{n=1}^\infty$  is convergent and

$$\lim_{n \rightarrow \infty} x_n = T(\lim x_n, \lim x_n, \dots, \lim x_n).$$

If in addition we suppose that

$$G_p(T(u, u, \dots, u), T(v, v, \dots, v), T(w, w, \dots, w)) < G_p(u, v, w) \quad (2.11)$$

holds for all  $u, v, w \in X$ , with  $u \neq v \neq w$ , then  $x$  is the unique point in  $X$  with  $T(x, x, \dots, x) = x$ .

**Remark 2.1.** Theorem 2.3 is generalization of corollary 2.5, as the condition (2.9) implies the conditions (2.4) and (2.6). Actually,

$$\begin{aligned} \lambda_1 G_p(x_1, x_2, x_3) + \lambda_2 G_p(x_2, x_3, x_4) + \dots + \lambda_k G_p(x_i, x_{i+1}, x_{i+2}) \\ \leq (\lambda_1 + \lambda_2 + \dots + \lambda_k) \max_{1 \leq i \leq k} \{G_p(x_i, x_{i+1}, x_{i+2})\} \quad (2.12) \end{aligned}$$

and  $\lambda_1 + \lambda_2 + \dots + \lambda_k < 1$ . Beside, for any  $u, v, w \in X$ , with  $u \neq v \neq w$ , from (2.9) we have

$$\begin{aligned}
 G_p(T(u, u, \dots, u), T(v, v, \dots, v), T(w, w, \dots, w)) &\leq G_p(T(u, u, \dots, u), T(u, u, \dots, u, v), T(u, u, \dots, u, v)) + \\
 &\quad G_p(T(u, u, \dots, u, v), T(u, u, \dots, u, v, v), T(u, u, \dots, u, v, v)) + \dots + \\
 &\quad G_p(T(v, w, \dots, w), T(w, w, \dots, w), T(w, w, \dots, w)) - \\
 &\quad \{G_p(T(u, u, \dots, u, v), T(u, u, \dots, u, v), T(u, u, \dots, u, v)) + \\
 &\quad G_p(T(u, u, \dots, u, v, v), T(u, u, \dots, u, v, v), T(u, u, \dots, u, v, v)) + \dots + \\
 &\quad G_p(T(u, w, \dots, w), T(u, w, \dots, w), T(u, w, \dots, w))\} \\
 &\leq G_p(T(u, u, \dots, u), T(u, u, \dots, u, v), T(u, u, \dots, u, v)) + \\
 &\quad G_p(T(u, u, \dots, u, v), T(u, u, \dots, u, v, v), T(u, u, \dots, u, v, v)) + \dots + \\
 &\quad G_p(T(v, w, \dots, w), T(w, w, \dots, w), T(w, w, \dots, w)) \\
 &\leq \lambda_1 G_p(u, v, w) + \lambda_2 G_p(u, v, w) + \dots + \lambda_k G_p(u, v, w) \\
 &= (\lambda_1 + \lambda_2 + \dots + \lambda_k) G_p(u, v, w) < G_p(u, v, w)
 \end{aligned}$$

and, as a result, (2.9) implies (2.6).

### 3 Conclusion

Nazir and Abbas [21], proved common fixed point theorems of Presic type in partial metric space. Further Dhasmana [22], showed fixed point theorem by using Presic type mapping in  $G$ -metric spaces. Our works generalizes several similar results in the literature.

### Acknowledgements

The authors wish to thank the referees for their careful reading of the manuscript and valuable suggestions.

### Competing Interests

Authors have declared that no competing interests exist.

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